

CONSIDERATION OF UNCERTAINTY IN STRUCTURAL DESIGN OF RC FRAME SUBJECTED TO SEISMIC LOADING

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- Response of structure to seismic loading
- Fuzzy numbers and fuzzy arithmetic
- Response surface function
- Numerical example



General governing equation:

$$M \frac{d^2 d(t)}{dt^2} + C \frac{d d(t)}{dt} + K d(t) = f(t)$$

M mass matrix

C damping matrix

K stiffness matrix

f(t) load vector

d (t) vector of nodal displacements



Single Degree Subjected to Seismic Loading - Response Spectrum:

$$\ddot{v}(t) + 2 \,\xi \,\omega \,\dot{v}(t) + \omega^2 \,v(t) = f \,\ddot{v}_g(t)$$

v(t) relative displacement

 $\ddot{v}_g(t)$ ground acceleration

 ω natural frequency

g damping

f mode participation factor

<u>Duhamel Integral - Response Spectrum:</u>

$$v(t) = \frac{f}{\omega} \int_{0}^{t} -\ddot{v}_{g}(\tau) \sin \omega (t - \tau) e^{-\xi \omega (t - \tau)} d\tau$$

 τ time of load application

Displacement Response Spectrum:

$$S_d(\omega) = v(\omega)_{\text{max}}$$

Velocity Response Spectrum:

$$S_v(\omega) = \omega S_d(\omega)$$

Acceleration Response Spectrum:

$$S_a(\omega) = \omega^2 S_d(\omega)$$



Natural Vibration:

$$(K - \omega^2 M)u = 0$$

u eigenmode

Vibration of Structure Induced by Seismic Loading:

$$\mathbf{M} \ddot{\mathbf{d}}(t) + \mathbf{C} \dot{\mathbf{d}}(t) + \mathbf{K} \mathbf{d}(t) = -\mathbf{M} \mathbf{s} \ddot{\mathbf{v}}_{g}(t)$$

s horizontal or vertical displacement

<u>Unknown Displacements</u>:

$$d(t) = U v(t)$$

U matrix containing eigenmodes in its columns

Vibration of Structure Caused by Seismic Loading:

$$\boldsymbol{U}^{T} \boldsymbol{M} \boldsymbol{U} \ddot{\boldsymbol{v}}(t) + \boldsymbol{U}^{T} \boldsymbol{C} \boldsymbol{U} \dot{\boldsymbol{v}}(t) + \boldsymbol{U}^{T} \boldsymbol{K} \boldsymbol{U} \boldsymbol{v}(t) = -\boldsymbol{U}^{T} \boldsymbol{M} \boldsymbol{s} \ddot{\boldsymbol{v}}_{g}(t)$$

Natural Vibration:

$$\ddot{v}_i(t) + 2\xi_i \,\omega_i \,\dot{v}_i(t) + \omega_i^2 \,v_i(t) = f_i \,\ddot{v}_g(t)$$

i index denoting eigenmode

Maximum modal response of *i*-th period:

$$y(T_i)_{\text{max}} = \frac{S_a(\omega_i)}{\omega_i^2}$$

 T_i period of *i*-th mode

Maximum modal displacement of *i*-th mode:

$$\boldsymbol{d}_{i} = \left(\boldsymbol{u}_{i}^{T} \boldsymbol{M} \boldsymbol{s} y(T_{i})_{\text{max}}\right) \boldsymbol{u}_{i}$$



Displacements for calculation of internal forces:

$$\boldsymbol{d} = \sum_{i=1}^{n} \left(y(T_i)_{\text{max}} \boldsymbol{u}_i^T \boldsymbol{M} \boldsymbol{s} \right) \boldsymbol{u}_i$$

n number of eigenmodes

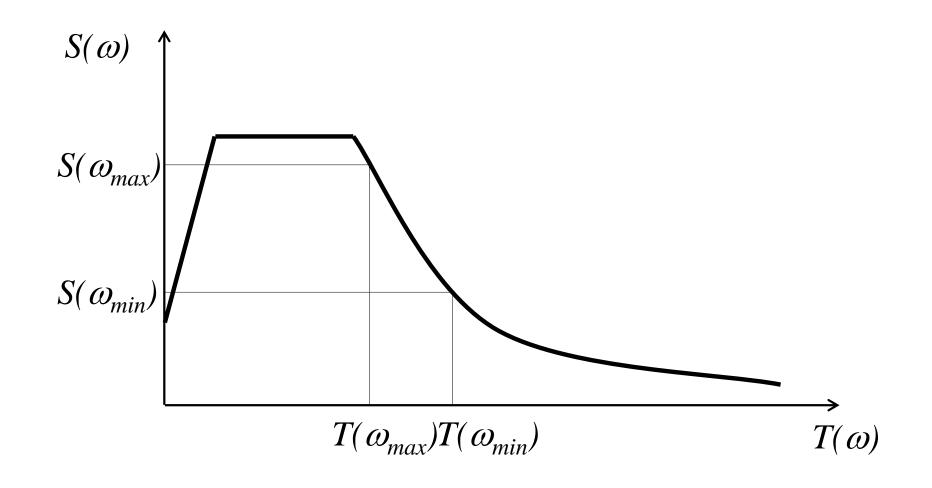
Equation for calculation of internal forces:

$$f = K d$$

K stiffness matrix



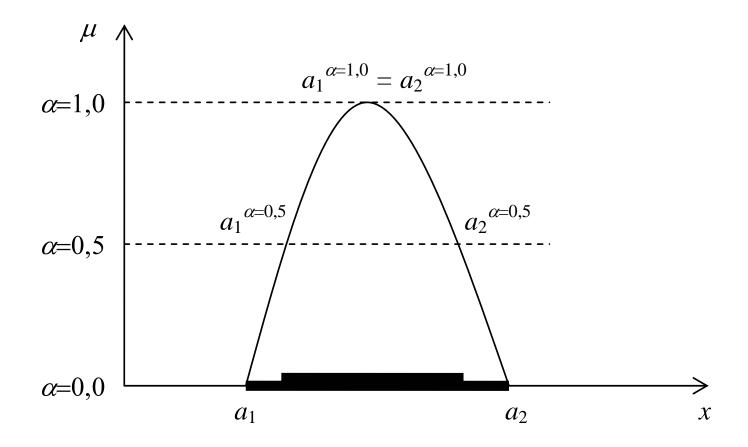
Example of response spectrum:



Fuzzy Numbers

A fuzzy number is a fuzzy set defined on the set of real numbers.

$$A = \{(x, \mu_A(x)) \mid x \in X\}$$



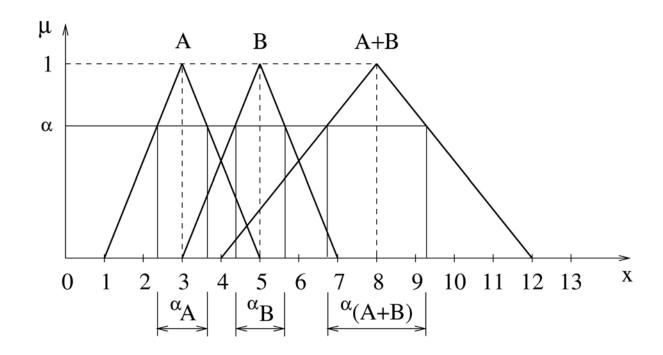


Fuzzy Arithmetic

Fuzzy operation are based on the extension principle

$$\mu_{A*B}(z) = \bigcup_{z=x*y} (\mu_A(x) \wedge \mu_B(y))$$

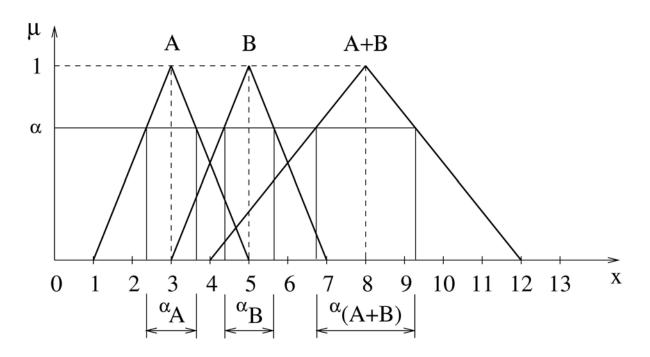
$${}^{\alpha}(A*B) = {}^{\alpha}A * {}^{\alpha}B \longrightarrow A*B = \bigcup_{\alpha \in [0,1]} {}^{\alpha}(A*B)$$





Fuzzy Arithmetic

$${}^{\alpha}(A*B) = {}^{\alpha}A * {}^{\alpha}B \longrightarrow A*B = \bigcup_{\alpha \in [0,1]} {}^{\alpha}(A*B)$$



Arithmetic operations on α -cuts are interval arithmetic operations

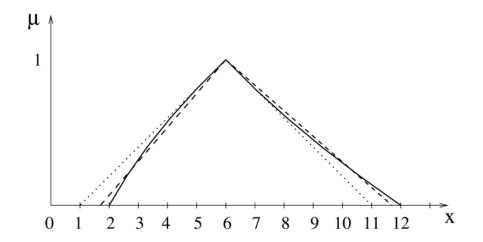
$${}^{\alpha}A(+)^{\alpha}B = \left[\underline{a}_{\alpha}; \overline{a}_{\alpha}\right] + \left[\underline{b}_{\alpha}; \overline{b}_{\alpha}\right] = \left[\underline{a}_{\alpha} + \underline{b}_{\alpha}; \overline{a}_{\alpha} + \overline{b}_{\alpha}\right]$$



Fuzzy Arithmetic

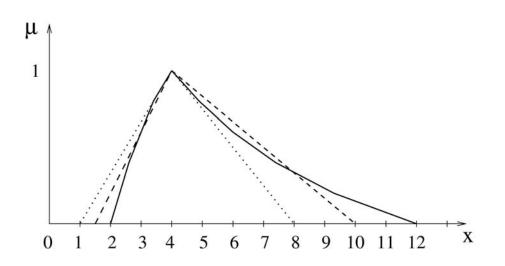
Examples of results of fuzzy arithmetic operations

Multiplication:



Division:







Response Surface Function

General response of a structure:

$$\widetilde{y} = \mathcal{F}(\widetilde{x}),$$
 Input: $\widetilde{x} \in \widetilde{X}$ Output: $\widetilde{y} \in \widetilde{Y}$

Approximation of \mathcal{F} in order to minimize necessary number of computation runs

Example:
$$f^{(k)}(x) = a^{(k)} + \sum_{i=1}^{n} b_i^{(k)} x_i + \sum_{i=1}^{n} \sum_{j=1}^{n} c_{ij}^{(k)} x_i x_j,$$

$$W_1 \qquad W_2$$

Response Surface Function

Approximation of \mathcal{F} :

$$f^{(k)}(x) = a^{(k)} + \sum_{i=1}^{n} b_i^{(k)} x_i + \sum_{i=1}^{n} \sum_{j=1}^{n} c_{ij}^{(k)} x_i x_j,$$

Coefficients are obtained by the least square method.

$$F^{(k)}(a^{(k)},b_i^{(k)},c_{ij}^{(k)}) = \sum_{i=1}^s \left(f^{(k)}(\boldsymbol{x}^{[i]}) - y_k^{[i]}\right)^2.$$

In our case, the quadratic terms were omitted, which simplied further computation.



RC 2D frame:

Modulus of elasticity:

$$E = 30 \text{ GPa}$$

Density:

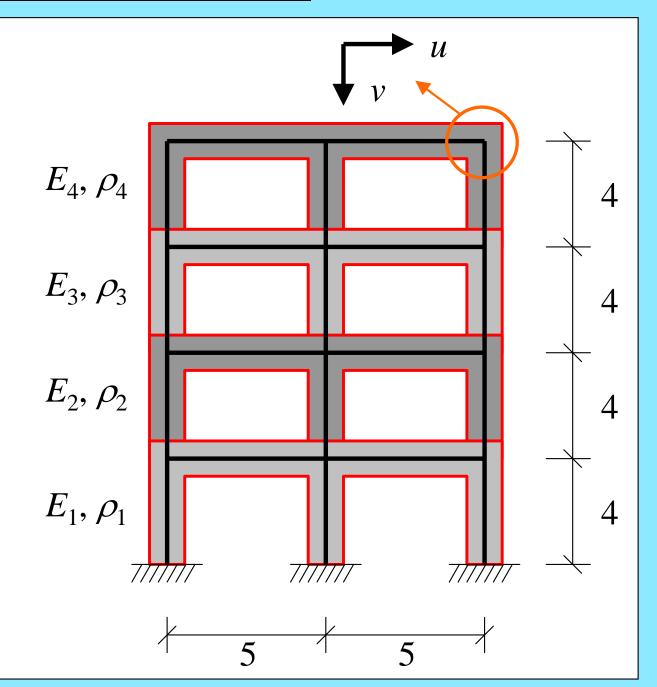
$$\rho = 2500 \text{ kg/m}^3$$

Quantities vary

by
$$\pm 10\%$$



fuzzy numbers





Objective of analysis:

First 5 natural vibration modes of 2D frame (5 frequencies and 5 mode shapes).

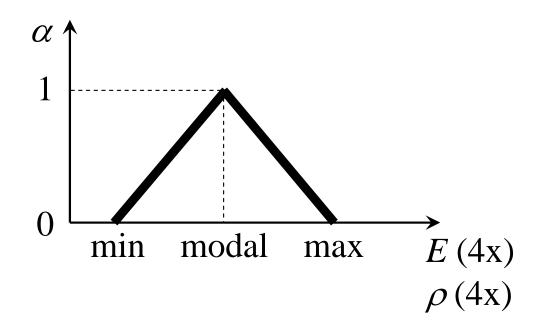
12	joints
x 2	displacements at joint
x 5	natural modes
120	
+ 5	natural frequencies
125	response surface functions

$$f^{(k)}(x) = b_1^{(k)} E_1 + b_2^{(k)} E_2 + b_3^{(k)} E_3 + b_4^{(k)} E_4 + b_5^{(k)} \rho_1 + b_6^{(k)} \rho_2 + b_7^{(k)} \rho_3 + b_8^{(k)} \rho_4 + b_9^{(k)}.$$



Coefficients of surface response function:

$$f^{(k)}(x) = b_1^{(k)} E_1 + b_2^{(k)} E_2 + b_3^{(k)} E_3 + b_4^{(k)} E_4 + b_5^{(k)} \rho_1 + b_6^{(k)} \rho_2 + b_7^{(k)} \rho_3 + b_8^{(k)} \rho_4 + b_9^{(k)}.$$

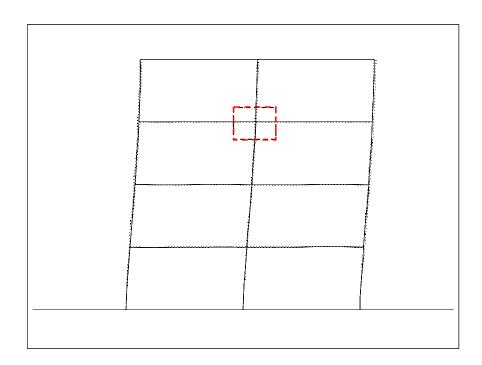


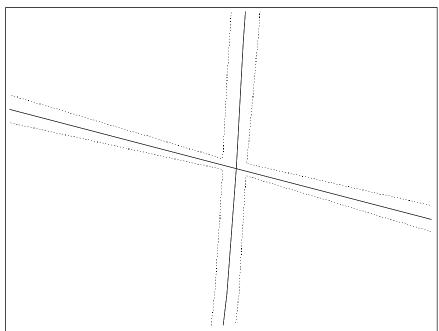
 $3^{2x4} = 6561$ combinations (deterministic computation runs)



Results:

Modal shape 1

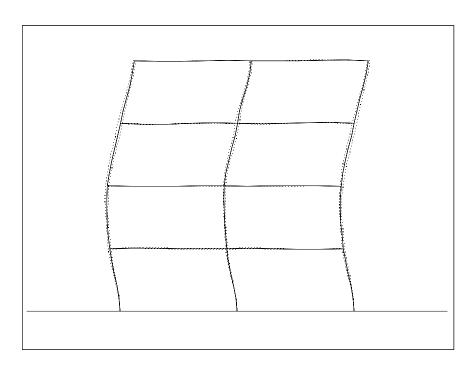


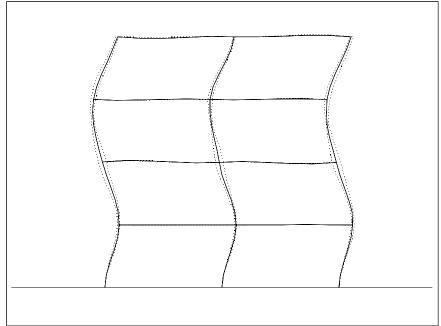




Results:

Modal shape 2 and modal shape 3

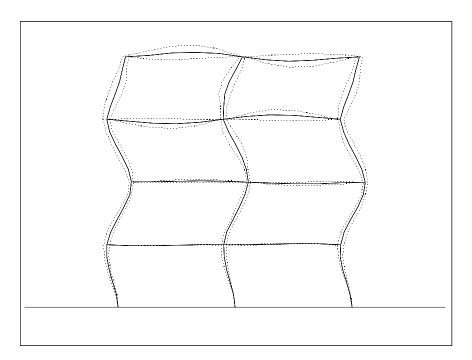


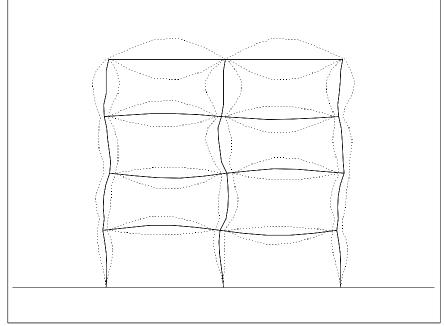




Results:

Modal shape 4 and modal shape 5

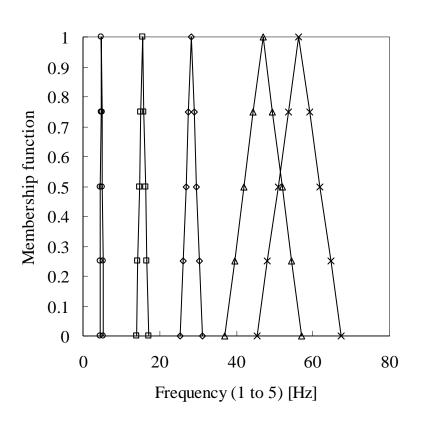


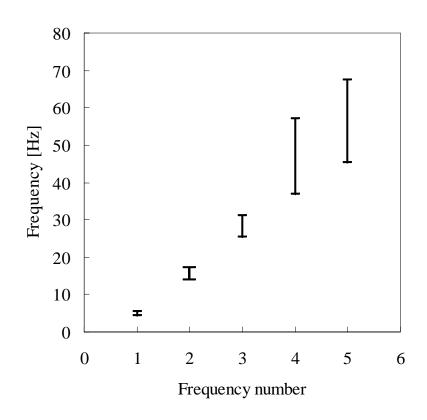




Results:

First 5 natural frequencies



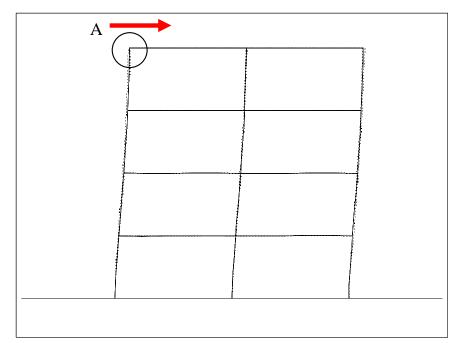


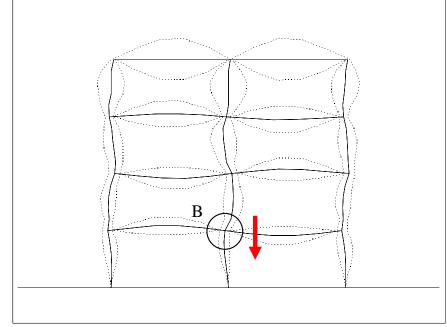


Comparison btw response surface function and true fuzzy result:

Modal shape 1

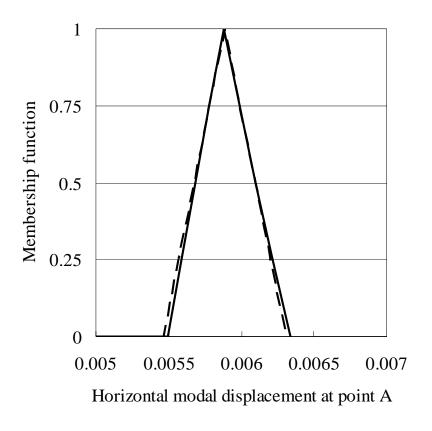
Modal shape 5

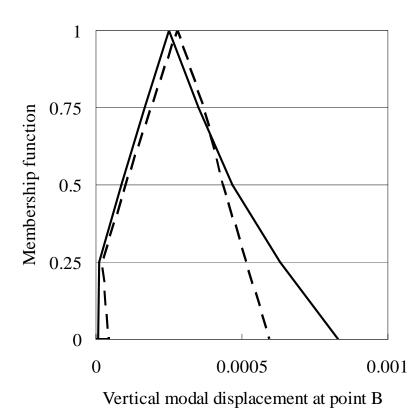






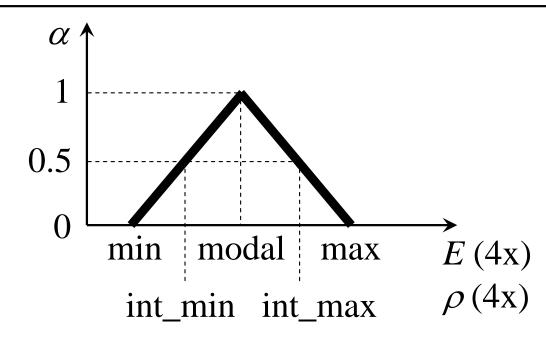
Comparison btw response surface function and true fuzzy result:





Verification of necessary number of α -cuts:

 $3^{2x4} = 6561$ combinations (deterministic computation runs)

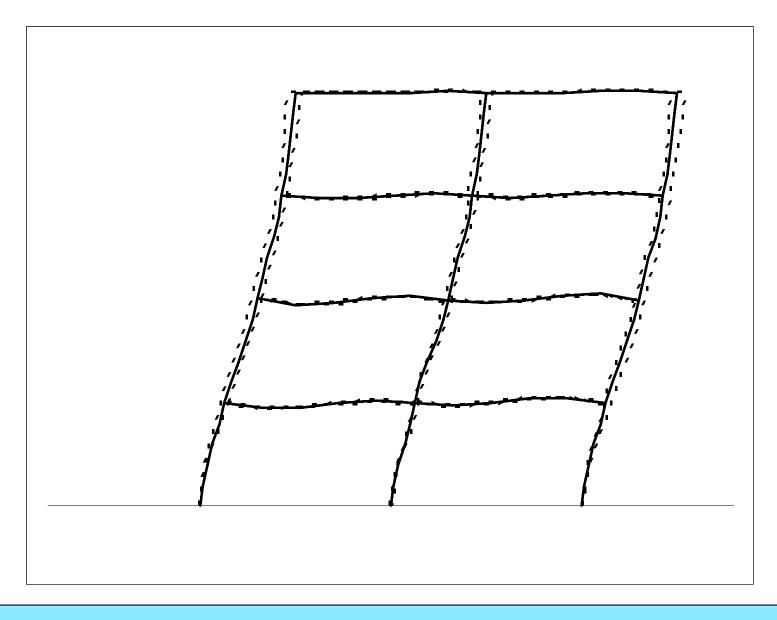


 $5^{2x4} = 390,625$ combinations (deterministic computation runs)

..... negligible improvement in accuracy.

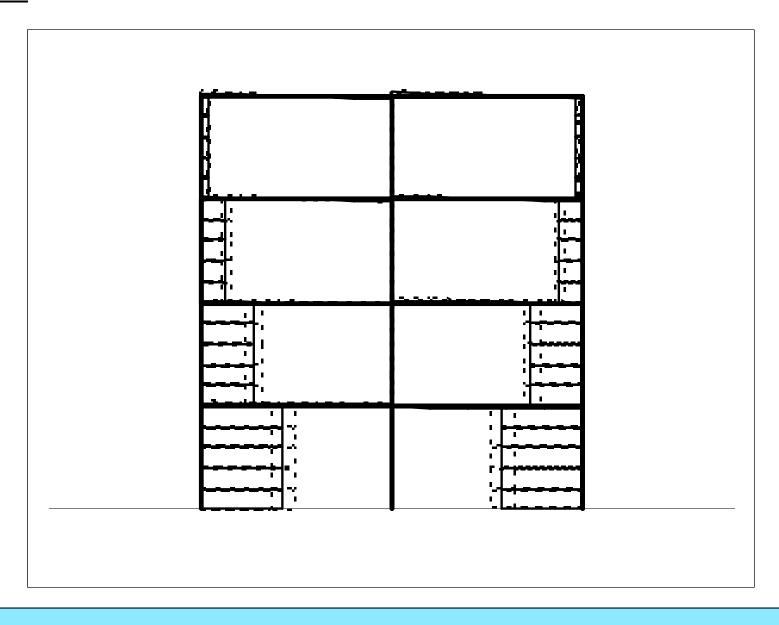


Results: Distribution of displacements



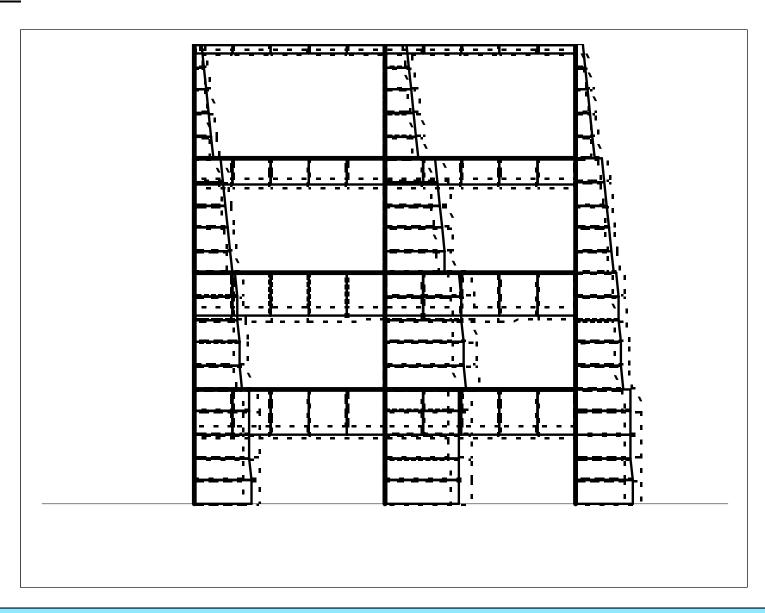


Results: Distribution of normal forces



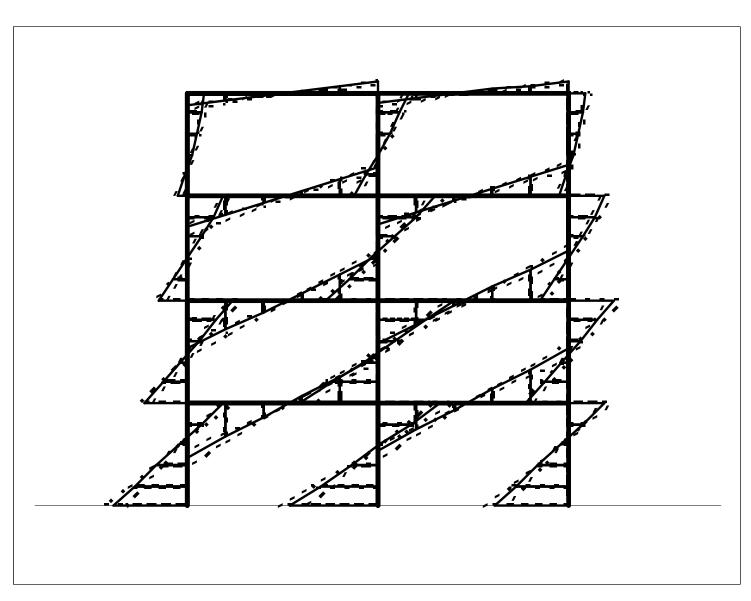


Results: Distribution of shear forces





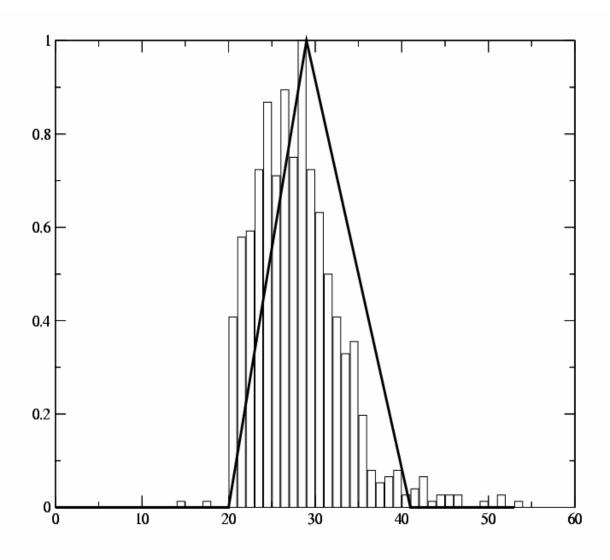
Results: Distribution of bending moments





Construction of Input Parameters

Compressive strength





Conclusions

- 1) The concept of fuzzy earthquake design based on response spectrum analysis was shown.
- 2) Fuzzy dynamic finite element method can be supplemented with the surface response function concept which increases computational efficiency.
- 3) It is hinted that input and output data collected through combinations of only three values (minimum, modal value, maximum) yield surface response functions with errors up to 5% from true results for dominant responses.
- 4) This method can serve as a tool for verification that the structural response is within design limits even if the input data contain uncertainty.