

Comparison of health monitoring strategies for a gradually deteriorating system in a stressful environment

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Overview & Outline

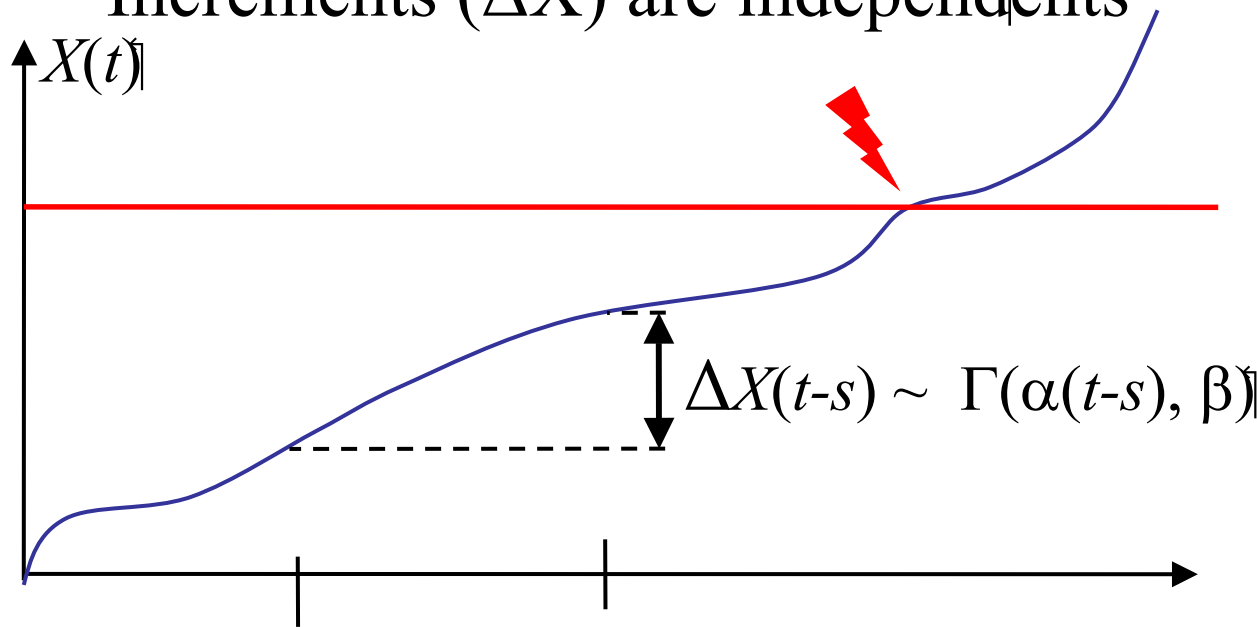
- Introduction: problem statement
- Description of the system
- Maintenance strategies
- Numerical results
- Summary & conclusions

Introduction

- Objective : Develop different maintenance strategies based on the knowledge level on the system:
 - a cumulative deterioration process
 - a stress process:
 - a priori knowlegde
 - information continuously available

System Description

- Deterioration process: Gamma process
 - $X(t)$ = deterioration variable
 - Increments (ΔX) are independent



$$E(X(t)) = \frac{\alpha}{\beta} t$$

$$V(X(t)) = \frac{E(X(t))}{\beta}$$

System Description

- Stress process
 - $Y_t=1$: the system is stressed
 - $Y_t=0$: the system is not stressed
 - The time intervals between successive state changes are exponentially distributed
- Impact of the stress on the deterioration process:

$$Y_{(t-s)} = 0 : X_{(t-s)} \sim \Gamma(\alpha(t-s), \beta)$$

$$Y_{(t-s)} = 1 : X_{(t-s)} \sim \Gamma(\alpha(t-s)e^\gamma, \beta)$$

$$\text{Finally: } X_{(t-s)} \sim \Gamma(\alpha(t-s)e^{\gamma y}, \beta)$$

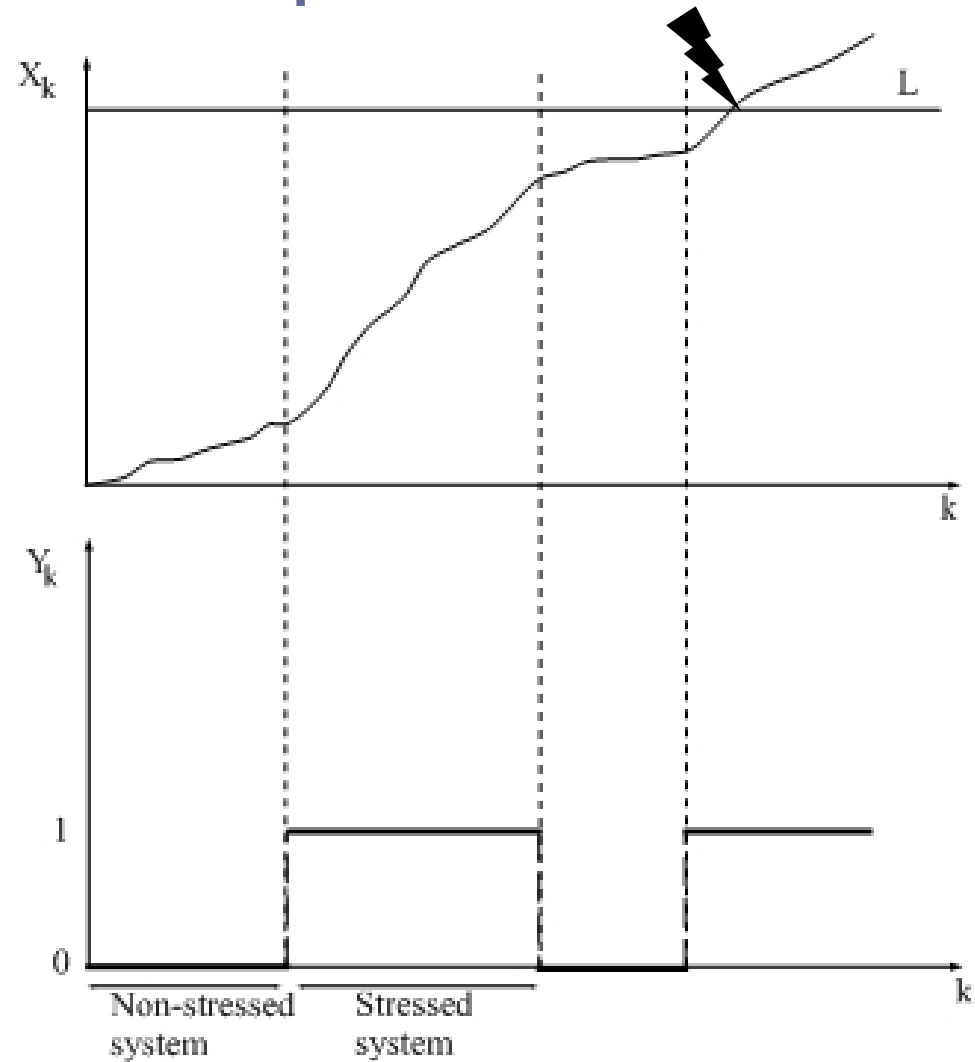
System Description

- In average the mean of the shape parameter:

$$\bar{\alpha} = \alpha(e^{\gamma} + \bar{r}(1 - e^{\gamma}))$$

- Where \bar{r} is the mean time elapsed in the stressed state and $r(t)$ is the actual proportion of time elapsed in the stressed state

System Description

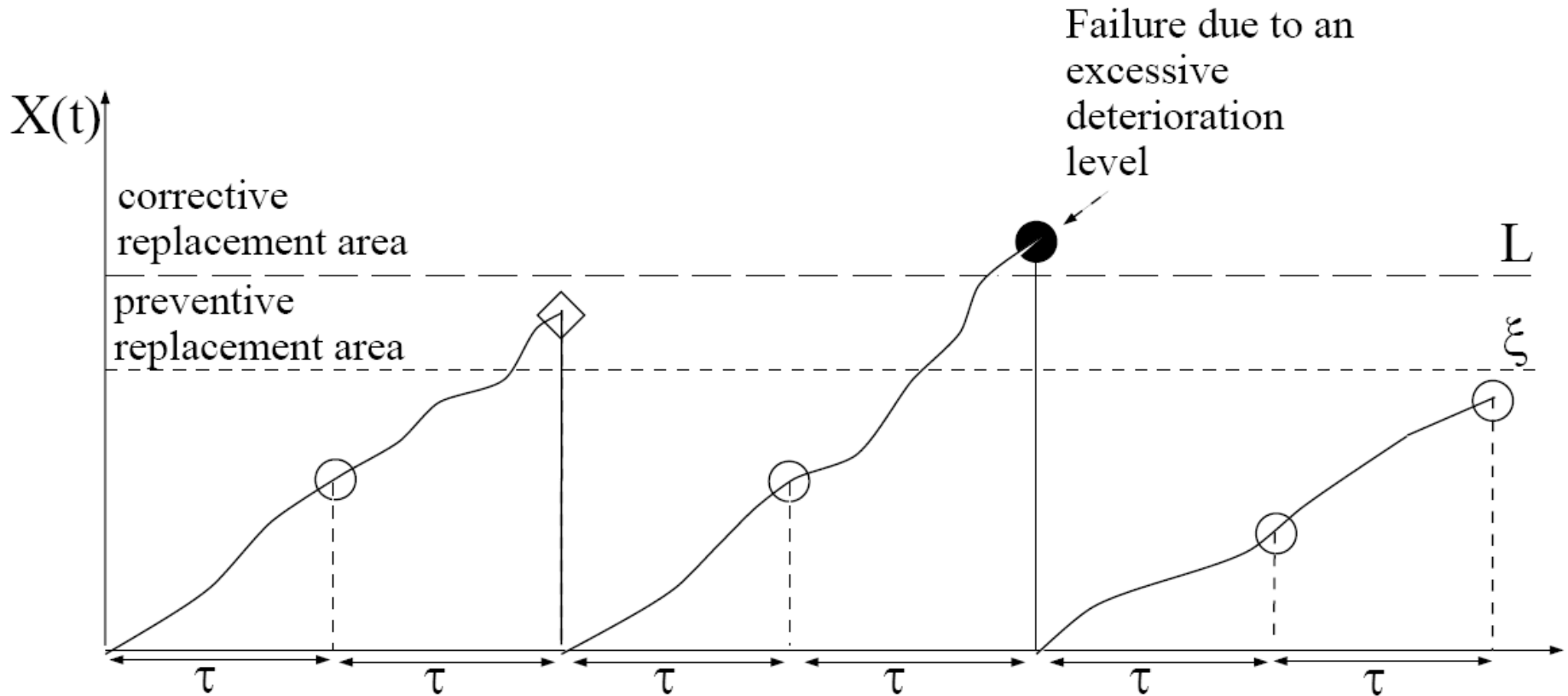


Stationary maintenance policy

Stress process: only an a priori knowledge (only \bar{r} is known)

- Condition-Based Maintenance for X_t
 - Periodic Inspection - τ - to measure the deterioration level (NDT techniques) - expensive inspection c_{ix}
- Preventive replacement if:
 - an inspection is performed
 - $X_t \in (\xi, L)$
 - cost: $c_{ix} + c_p$
- Corrective replacement if:
 - an inspection is performed
 - $X_t > L$
 - cost: $c_{ix} + c_c + c_u D_u$

Stationary maintenance policy



Performance of the Stationary Maintenance Policy

- Maintenance cost criterion

$$C_{\infty}(\tau, \xi) = \lim_{t \rightarrow \infty} \frac{C(t)}{t} = \frac{E(C(S))}{E(S)}$$

– C(t) :

$$C(t) = c_{ix} N_{ix}(t) + c_p N_p(t) + c_c N_c(t) + c_u D_u(t)$$

- Numerically evaluated

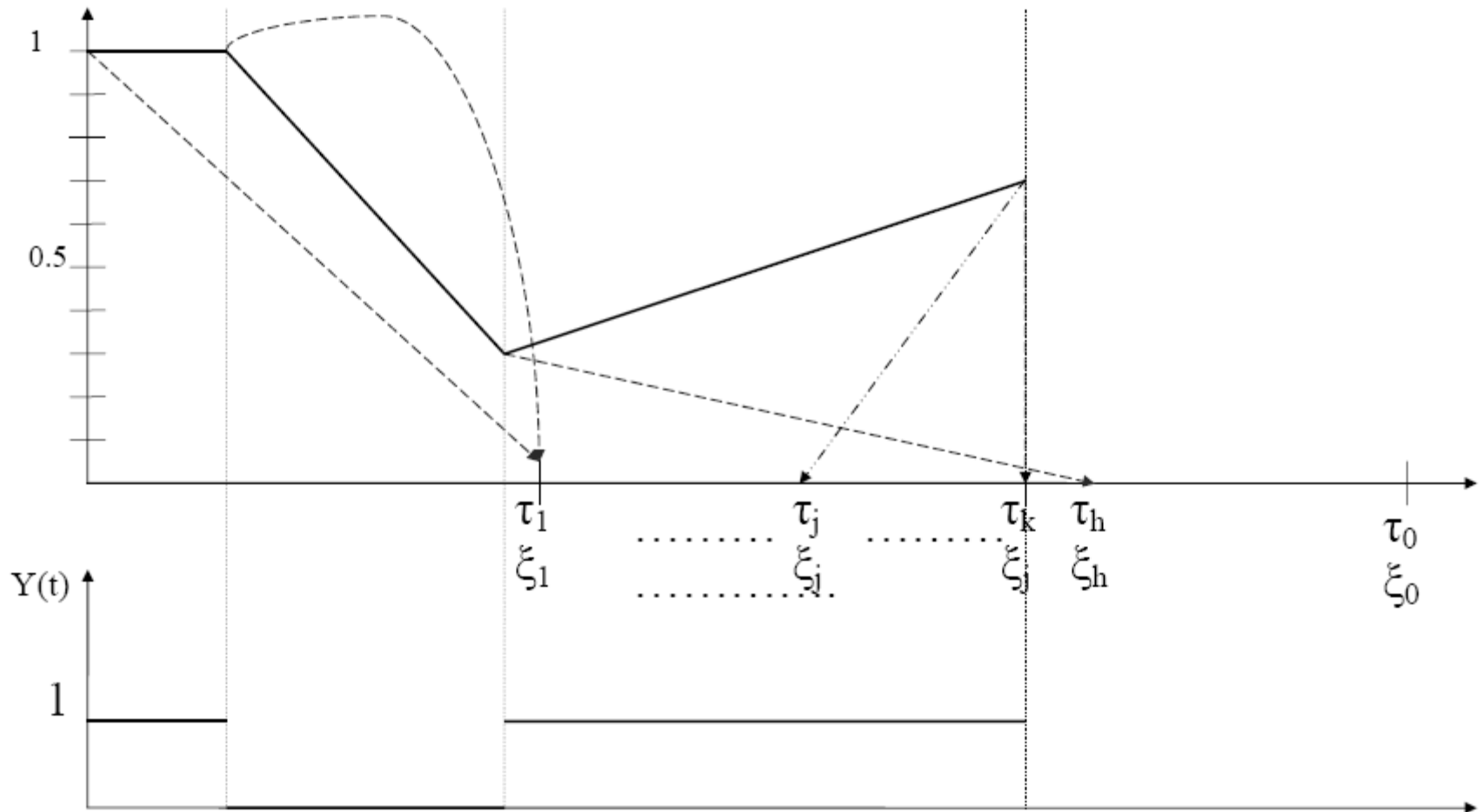
“Adaptive” maintenance policy

The stress covariate is continuously monitored

- $r(t)$: the actual proportion of time elapsed in the stressed state
- $(\tau_{r(t)}, \xi_{r(t)})$ the optimized decision parameters for stationary maintenance policy when $r(t) = \bar{r}$
- At each environmental state change: decision parameters are re-evaluated according to $r(t)$ $(\tau_{r(t)}, \xi_{r(t)})$
 - If the new inspection period leads to an inspection time lower than the present time, the system is inspected immediately with the following decision parameters $(t, \xi_{r(t)})$
 - Limit cases:
 - System never stressed: $r(t)=0$; decision parameters (τ_0, ξ_0)
 - System always stressed: $r(t)=1$; decision parameters (τ_1, ξ_1)

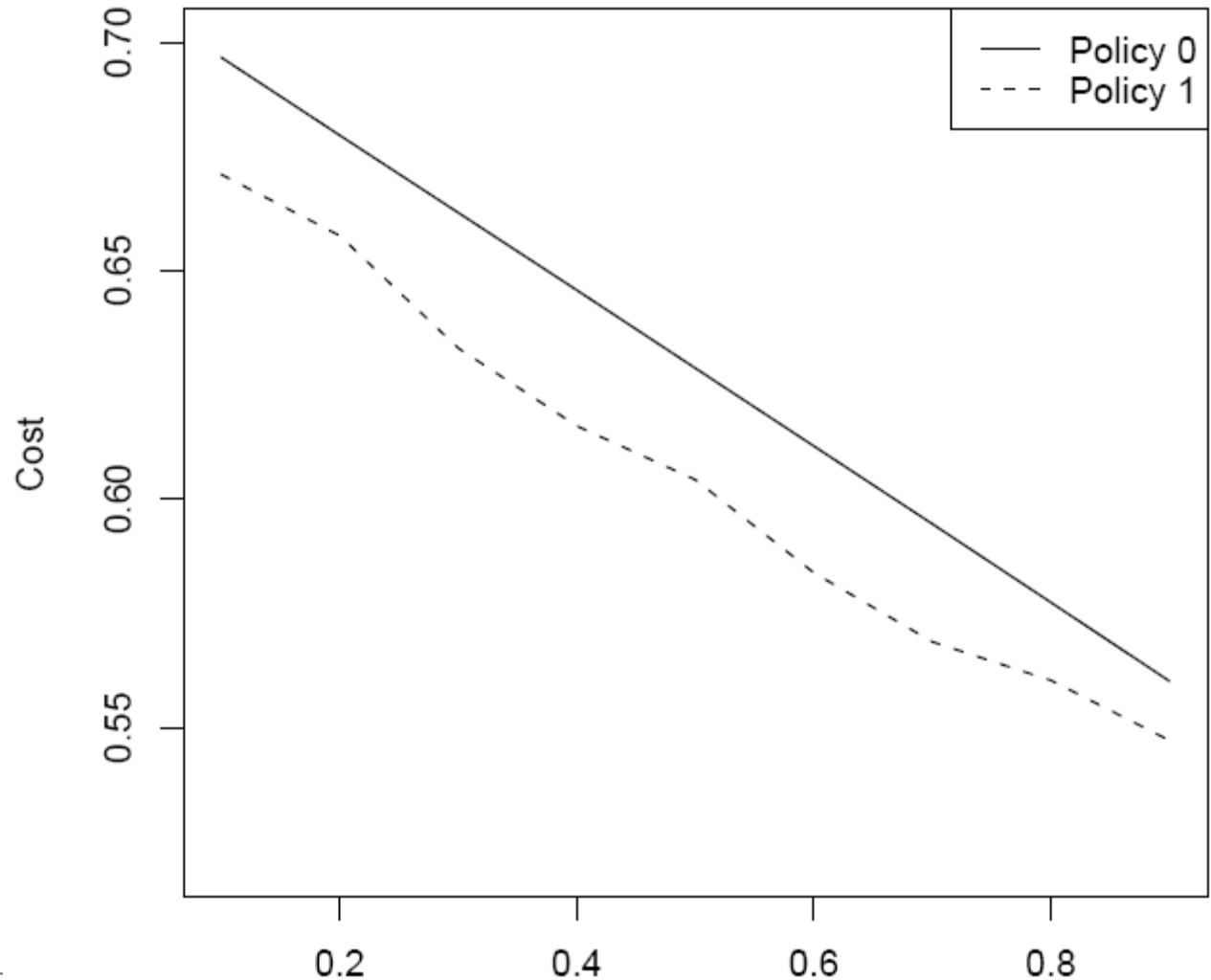
Adaptive maintenance policy

Proportion of time
elapsed in the stress
state: $r(t)$



Performance of the maintenance policy

4% cost saving
with the adaptive
maintenance
policy (Policy 1)



Summary & conclusions

- Modelling of the relationship between the system performance and the associated operating environment
- Development of two maintenance strategies:
 - One based on the a priori knowledge of the stress process
 - One based on the continuous available information on the stress process

Next steps and future work

- Development of the mathematical model for the adaptive maintenance strategy
- Study of the model sensitivity analysis