

The Risk Monitoring System COSMOS for At-Power and Shutdown Conditions

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1. Background

- Utilization of PSA
 - Identification of High Risk Equipments and Systems
 - Decision of Maintenance Planning of Equipments and Systems
 - Modification of Tech-Spec, etc
- Status of Utilization of Risk Information in Japan
 - Preparing Regulatory Guideline for PSA
 - Preparing Industrial Standard and Guideline for PSA
 - Preparing Application and Usage Method of Risk Information in NPP



In near future, the **risk monitoring system is needed** for utilization of risk information in each Japanese NPP.



We have developed risk monitoring system, COSMOS.
(COSMOS : Continuous Online Safety MOnitoring System)

2. Outline of COSMOS

- COSMOS is a level-1 and internal event risk monitoring tool up to now.
- COSMOS has two separated modules, **COSMOS-FP (for at-power)** and **COSMOS-SD (for shutdown)**.
 - Usage method is different between at-power and shutdown, so we have developed COSMOS-FP and COSMOS-SD by different quantification methods.
- COSMOS has completely linkage to RISKMAN for Windows (RMW) and the model.
 - COSMOS does not require special PSA models for RMW and CDF sequences which previously stored.

3. Feature of COSMOS

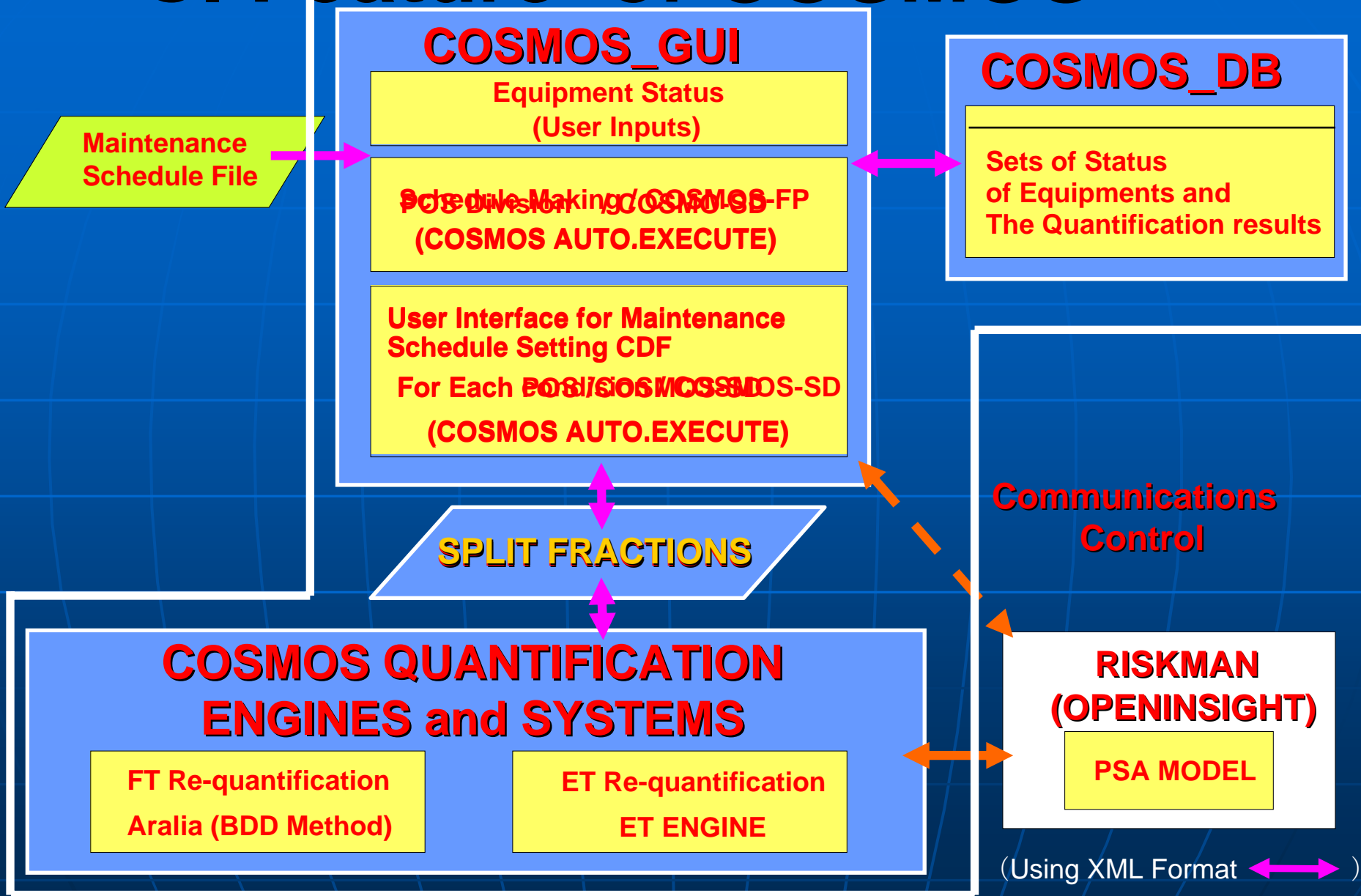
A Conventional Event Tree Linking Method Tool

- Quantify Core damage frequency based on the core damage **sequences or cutsets previously stored**.
 - The calculation precision is strongly dependent on the number of the prepared sequences.
- Have to identify the outage equipments, before picking up core damage sequences.

COSMOS

- **Quantify Core damage frequency directly from FTs and ETs quantification**.
 - COSMOS does not require the core damage sequences or cutsets previously stored.
- Treat all basic events for the input conditions.
(COSMOS-FP)

3. Feature of COSMOS



3.(1) COSMOS-FP (for at-power)

- Assume to use COSMOS-FP for **scheduling of at-power on-line maintenance**.
- Restore sets of status of equipments and the quantification results to the database. COSMOS-FP utilizes the **database for speeding calculation**.
- Have a feature of **successive execution of systems and ETs** corresponding to the on-line maintenance equipments.

3.(1) COSMOS-FP

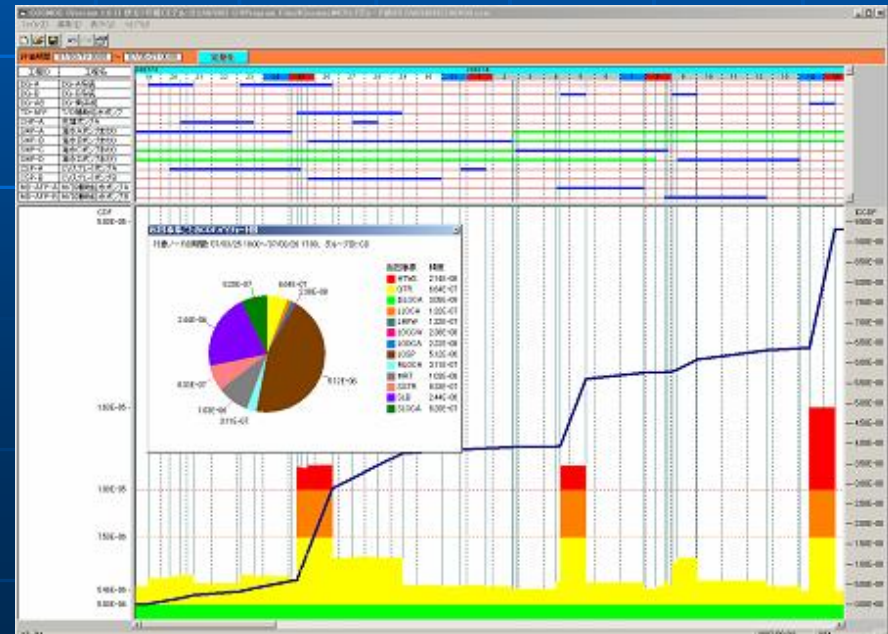
For On-line Maintenance Scheduling and Risk Evaluation (COSMOS_GUI)

Input Generation

- Gantt Chart Operation
- Inputs referred to Calendar
- Inputs from Formatted file (XML)
- “In-service” or “Standby“ or “Out of Service” Switching

Result Indication

- Time dependent CDF and/or ICCDP/Cumulative ICCDP Outputs
- The CDF sequence outputs by each time phase
- The core damage frequency outputs for every IE by each time phase



3.(1) COSMOS-FP

For Successively Execution of Systems and ETs corresponding to Exact Plant Conditions

1. Set the exact equipments status

- in-service, standby or out of service of PSA equipments

2. Re-quantify the system failure probabilities based on exact equipments status

- the failure probability of maintenance equipment as 1.0
- Based on BDD method using ARALIA

3. Re-quantify Event Trees using updated system failure probabilities

- We developed quantification Engines and successively quantification system cooperated.
- COSMOS-FP stored sets of status of equipments and the quantification results (CDFs for each IE and the sequences of CDF) to COSMOS_DB.

3.(2) COSMOS-SD (for shutdown)

- COSMOS-SD is utilized for the **risk evaluation during shutdown.**
- Equipments are normally maintained each system units. So **COSMOS-SD does not re-quantify FTs** based on basic events **but re-quantify only ETs** based on systems. This logic is similar to **ATORAS.**
- **COSMOS-SD divides Shutdown into POSs automatically.** Each POS is divided depending on RCS water level and the cooling systems (SG or RHR). Moreover they are divided by status of the mitigation systems.

3.(2) COSMOS-SD

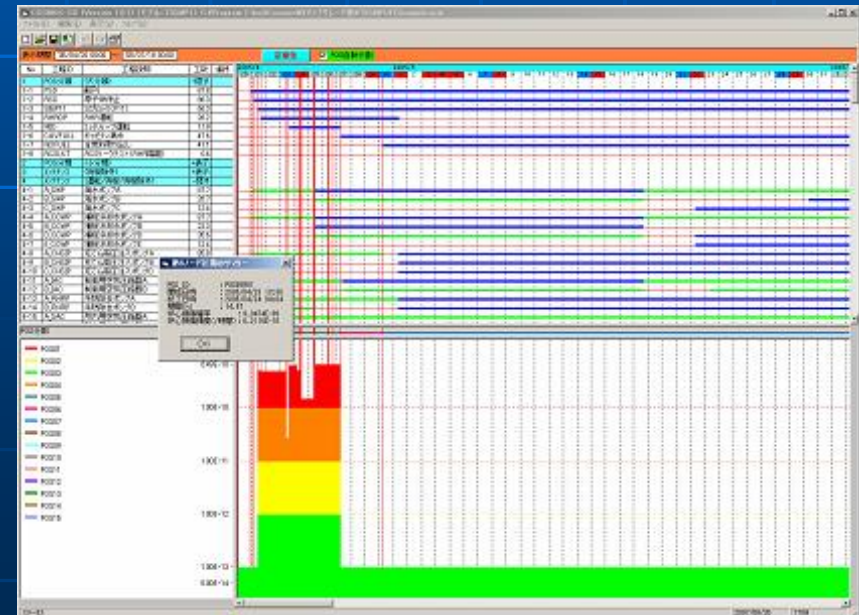
For Shutdown Scheduling and Risk Evaluation (COSMOS_GUI)

- Input Generator

- Gantt Chart Operation
- Inputs through Calendar
- Inputs from Formatted file (XML)
- “In-service” or “Standby” or “Out of service” Switching

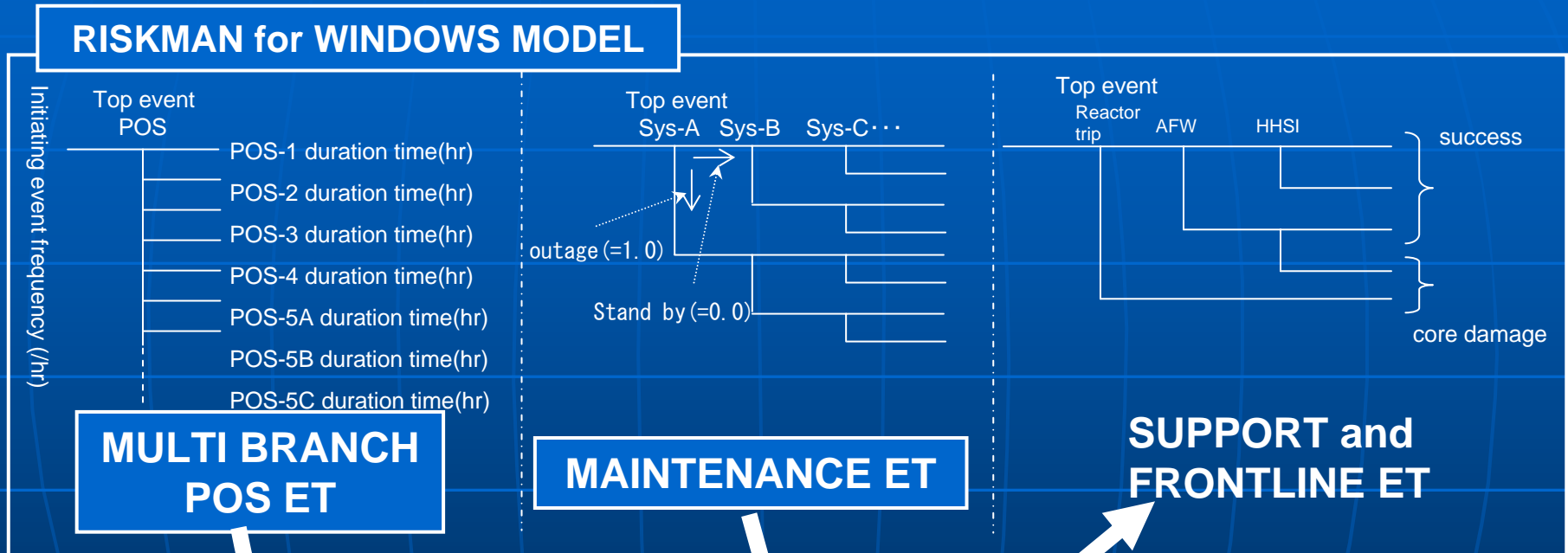
- Result indication

- Time dependent CDF
- The CDF sequence outputs by each POS
- The core damage frequency outputs for every IE by each POS



3.(2) COSMOS-SD

For improvement of a shutdown RMW model



- Get all POSs CDF once quantification
- Maintenance System Status for Each POS

4. Further Enhancements

- Quantification Speed-up with Event Tree Engine Changing (Bin-cutoff setting to 0)
- Adding to the Importance Calculation Function
- Calculation Logic of “COSMOS-SD” Based on ETs Re-quantification Shifting to “COSMOS-FP” based on FTs and ETs Re-quantification.
- Linkage Developing to the Maintenance Schedulers (responded to the user request)

5. Conclusions

- We have developed the risk monitoring system **COSMOS** which has two separated modules “**COSMOS-FP**” (for **at-power**) and “**COSMOS-SD**” (for **shutdown**) with the aim of each utilizations.
- **COSMOS-FP** has a feature of **successive execution of FTs and ETs**.
- **COSMOS-SD** does not re-quantify FTs based on basic events but re-quantify only ETs considering systems maintenance.
- COSMOS has completely linkage to RMW and the model.
If you have the RMW model for **at-power or shutdown**, you can use **COSMOS-FP** or **COSMOS-SD** easily (without much effort).
- If you're interested, please send an e-mail to kohya@neltd.co.jp.